

Kalman Duality as Chu Duality

Contents

1	The basic linear system	1
2	The Hankel Chu object	2
3	Factorization through state and costate	2
4	Kalman duality is Chu duality	3
5	Biextensional collapse and minimal realization	3

1 The basic linear system

Let k be a field and let

$$X, U, Y \in \mathbf{Vect}_k^{\text{fd}}.$$

A finite-dimensional continuous-time linear system is given by

$$\Sigma = (X, U, Y, A, B, C),$$

with

$$A : X \rightarrow X, \quad B : U \rightarrow X, \quad C : X \rightarrow Y,$$

and equations

$$\dot{x} = Ax + Bu, \quad y = Cx.$$

Its Kalman dual is

$$\Sigma^\vee = (X^*, Y^*, U^*, A^*, C^*, B^*),$$

that is,

$$\dot{\xi} = A^*\xi + C^*\eta, \quad \zeta = B^*\xi.$$

The local system presentation is stateful: the vector field depends on both the present state and the present input,

$$X \times U \longrightarrow TX, \quad (x, u) \longmapsto (x, Ax + Bu),$$

together with the readout $C : X \rightarrow Y$. This is the lens-like level of the construction.

2 The Hankel Chu object

Let

$$\mathcal{H}_\Sigma^+ = U[z] = \bigoplus_{m \geq 0} U z^m, \quad \mathcal{H}_\Sigma^- = Y^*[z] = \bigoplus_{n \geq 0} Y^* z^n.$$

Define

$$h_\Sigma : U[z] \times Y^*[z] \longrightarrow k$$

by

$$h_\Sigma(uz^m, \eta z^n) = \eta(CA^{m+n}Bu), \quad (1)$$

and extend bilinearly.

Definition 1. *The Hankel Chu object of Σ is*

$$\text{Chu}(\Sigma) = (U[z], Y^*[z], h_\Sigma) \in \text{Chu}(\mathbf{Vect}_k, k).$$

The coefficients $CA^r B$ are the Markov parameters of the system. The defining relation

$$h_\Sigma(zp, q) = h_\Sigma(p, zq)$$

expresses shift invariance.

3 Factorization through state and costate

Define the reachability map

$$\rho_\Sigma : U[z] \longrightarrow X, \quad \rho_\Sigma(uz^m) = A^m Bu,$$

and the transpose-observability map

$$\omega_\Sigma^\vee : Y^*[z] \longrightarrow X^*, \quad \omega_\Sigma^\vee(\eta z^n) = (A^*)^n C^* \eta.$$

Then

$$h_\Sigma(p, q) = \langle \omega_\Sigma^\vee(q), \rho_\Sigma(p) \rangle. \quad (2)$$

Thus the Hankel relation factors through the canonical evaluation

$$X^* \times X \longrightarrow k.$$

This factorization separates two roles:

past interventions or reachable histories	and	future observations or experiments.
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The state space is an intermediate realization of the external past–future pairing.

4 Kalman duality is Chu duality

The Chu dual of (P, N, e) is

$$(P, N, e)^\perp = (N, P, e^\top), \quad e^\top(n, p) = e(p, n).$$

Theorem 2 (Kalman–Chu duality). *For every finite-dimensional linear system Σ there is a canonical isomorphism*

$$\text{Chu}(\Sigma^\vee) \cong \text{Chu}(\Sigma)^\perp.$$

Equivalently, once the carriers are chosen as input jets and output-covector jets, the Chu involution is exactly the Kalman transpose duality.

Proof. The positive carrier of $\Sigma^\vee$ is $Y^*[z]$, while its negative carrier is

$$(U^*)^*[z] \cong U[z]$$

by finite-dimensional reflexivity. For generators,

$$\begin{aligned} h_{\Sigma^\vee}(\eta z^n, u z^m) &= u(B^*(A^*)^{m+n}C^*\eta) \\ &= \eta(CA^{m+n}Bu) \\ &= h_\Sigma(uz^m, \eta z^n). \end{aligned}$$

Hence $h_{\Sigma^\vee} = h_\Sigma^\top$ under the canonical identifications. □

5 Biextensional collapse and minimal realization

Let

$$\mathcal{R} = \text{span}\{A^m Bu \mid m \geq 0, u \in U\}$$

be the reachable subspace, and let

$$\mathcal{N} = \bigcap_{n \geq 0} \ker(CA^n)$$

be the unobservable subspace.

The left radical of the Hankel pairing is

$$\text{Rad}_L(h_\Sigma) = \rho_\Sigma^{-1}(\mathcal{N}),$$

while the right radical is

$$\text{Rad}_R(h_\Sigma) = (\omega_\Sigma^\vee)^{-1}(\mathcal{R}^\perp).$$

Consequently,

$$U[z]/\text{Rad}_L(h_\Sigma) \cong \mathcal{R}/(\mathcal{R} \cap \mathcal{N}).$$

The latter is the minimal reachable-observable state space

$$X_{\min} = \mathcal{R}/(\mathcal{R} \cap \mathcal{N}).$$

Dually,

$$Y^*[z]/\text{Rad}_R(h_\Sigma) \cong X_{\min}^*.$$

Proposition 3. *The biextensional collapse of $\text{Chu}(\Sigma)$ is, up to the canonical identifications induced by reachability and observability,*

$$(X_{\min}, X_{\min}^*, \text{ev}).$$

Its dimension is the Hankel rank.

Because $X_{\min}$ is finite-dimensional, the reduced pairing is not merely separated on both sides but perfect.